WHAT IS CLAIMED IS:

1.   (Currently Amended) A <u>wireless</u> system <u>operable to issue commands to a robotic device according to a typematic rate of interface,</u> ~~for controlling operations associated with generating and detecting ultrasonic surface displacements on a remote object, the operations including obtaining information associated with the object,~~ the system including:

a processor <u>operably coupled to the robotic device, wherein the robotic device further comprises a laser ultrasonic non destructive evaluation (NDE) inspection system operable to generate and detect ultrasonic surface displacements on a remote object;</u>

<u>the</u> ~~a~~ laser ultrasonic system linked with the processor; and

a wireless communicator <u>operably interfaced to the processor wherein the wireless communicator is operable to generate at least one command signal based on the typematic rate of interface;</u>

~~the wireless communicator generating a command signal;~~

~~the processor receiving the command signal and operating the laser ultrasonic system based on the command signal~~

<u>the processor is operable to issue the at least one command signal to the robotic device wherein the processor is operable to issue a second command signal when the typematic rate of interface changes beyond a predetermined threshold.</u>

2.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 1 further including a restricted system.

3.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 2 wherein the restricted system includes a barrier.

4.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 3 wherein the lasing system is enclosed by the barrier.

5.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 3 wherein the wireless communicator opens the barrier.

6-11. Canceled.

12.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 1 wherein the lasing operations include controlling a robotic device.

13.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 12 wherein the wireless communicator generates a command signal associated with the robotic device.

14.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 12 wherein the wireless communicator generates a command signal based on the typematic rate of interface.

15.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 12 wherein the wireless communicator continuously generates a command signal based on a typematic rate of interface.

16.   (Currently Amended) The <u>wireless</u> system of ~~according to~~ claim 12 wherein the wireless communicator continuously generates a plurality of command signals based on the typematic rate of interface.

17-36. Canceled.

37.   (Currently Amended) A <u>wireless controller operable to issue commands to a robotic device according to a typematic rate of interface,</u> ~~for controlling operations associated with generating and detecting ultrasonic surface displacements on a remote object, the operations including obtaining information associated with the object,~~ the <u>wireless controller comprising:</u> ~~system including~~
   a processor <u>operably coupled to the robotic device, wherein the robotic device further comprises a high-energy density system;</u>
   ~~a laser ultrasonic system linked with the processor; and~~

a wireless communicator operably coupled to the processor wherein the wireless communicator is operable to generate at least one command signal based on the typematic rate of interface;

~~the communicator generating a command signal;~~

~~the processor receiving the command signal and operating the laser ultrasonic system based on the command signal.~~

the processor is operable to issue the at least one command signal to the robotic device wherein the processor is operable to issue a second command signal when the typematic rate of interface changes beyond a predetermined threshold.

38.   (New) A wireless controller operable to issue commands to a robotic device according to a typematic rate of interface, the system comprising:

a processor operably coupled to the robotic device, wherein the robotic device further comprises a laser ultrasonic system operable to generate and detect ultrasonic surface displacements on a remote object; and

a wireless communicator operably interfaced to the processor wherein the wireless communicator is operable to generate at least one command signal based on the typematic rate of interface; and

the processor is operable to issue the at least one command signal to the robotic device wherein the processor is operable to issue a second command signal when the typematic rate of interface changes beyond a predetermined threshold.

39.   (New) A controller operable to issue to an emergency stop command according to a typematic rate of interface, the controller comprising:

a processor operably coupled to the high-energy density system;

a wireless communicator operably coupled to the processor wherein the wireless communicator is operable to generate at least one command signal based on the typematic rate of interface;

the processor is operable to issue the at least one command signal to the high-energy density system wherein the processor is operable to issue the emergency stop command signal when the typematic rate of interface changes beyond a predetermined threshold.